



Figure similar

Article No. : 1FK7043-4CH71-1RH0

Client order no. :
Order no. :
Offer no. :
Remarks :

Item no. :
Consignment no. :
Project :

Engineering data	
Rated speed (100 K)	4,500 rpm
Number of poles	6
Rated torque (100 K)	2.6 Nm
Rated current	3.3 A
Static torque (60 K)	2.90 Nm
Static torque (100 K)	3.50 Nm
Stall current (60 K)	3.30 A
Stall current (100 K)	4.10 A
Moment of inertia	1.360 kgcm²
Efficiency	90.0 %

Physical constants	
Torque constant	0.85 Nm/A
Voltage constant at 20° C	54.0 V/1000*min ⁻¹
Winding resistance at 20° C	1.20 Ω
Rotating field inductance	13.6 mH
Electrical time constant	11.30 ms
Mechanical time constant	0.49 ms
Thermal time constant	40 min
Shaft torsional stiffness	9,000 Nm/rad
Net weight of the motor	6.6 kg

Mechanical data	
Motor type	Permanent-magnet synchronous motor
Motor type	High Dynamic
Shaft height	48
Cooling	Natural cooling
Radial runout tolerance	0.040 mm
Concentricity tolerance	0.08 mm
Axial runout tolerance	0.08 mm
Vibration severity grade	Grade A
Connector size	M23
Degree of protection	IP64
Design acc. to Code I	IM B5 (IM V1, IM V3)
Temperature monitoring	Pt1000 temperature sensor
Electrical connectors	Connectors for signals and power rotatable
Color of the housing	Standard (Anthracite RAL 7016)
Holding brake	with holding brake
Shaft end	Plain shaft
Encoder system	Encoder AM20DQI: absolute encoder 20 bits (resolution 1048576, encoder-internal 512 S/R) + 12 bits multi-turn (traversing range 4096 revolutions)

Optimum operating point	
Optimum speed	4,500 rpm
Optimum power	1.2 kW

Limiting data	
Max. permissible speed (mech.)	9,000 rpm
Max. permissible speed (inverter)	9,000 rpm
Maximum torque	10.0 Nm
Maximum current	12.5 A

Holding brake	
Holding brake version	Permanent-magnet brake
Holding torque	4.0 Nm
Power supply voltage	DC 24 V ± 10 %
Coil current	0.5 A
Opening time	70 ms
Closing time	30 ms
Highest braking work	150 J

Recommended Motor Module	
Rated inverter current	5 A
Maximum inverter current	15 A
Maximum torque	10.00 Nm